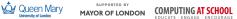
Teach A level Computing: Algorithms and Data Structures

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Course Outline

Representations of data structures: Arrays, tuples, Stacks, Queues, Lists **Recursive Algorithms** Searching and Sorting Hashing and Dictionaries, Graphs and Trees Depth and breadth first searching; tree traversals









• http://www.aqa.org.uk/subjects/computer-science-and-it/as-and-a- level/computer-science-7516-7517/subject-content-a-level/ fundamentals-of-algorithms









Graphs

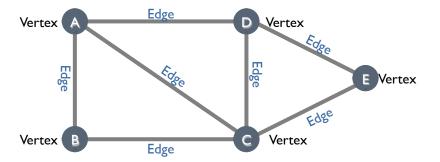








What is a graph



• Some resources may refer to nodes and arcs.....









Terminology

- A graph can have cycles (loops)
- A weighted graph has a value on the edge
- A directed graph has arrows to indicate direction
- A multigraph has multiple edges connecting the same vertices
- A tree is a type of graph where...
 - · All vertices are connected
 - The graph is undirected
 - There are no cycles



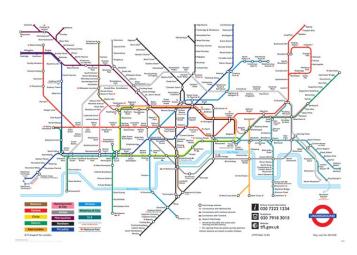






Uses of graphs

- Route planning and map
- Web page links
- Social media connection:
- Underground tube links
- etc











Representing graphs

- Graphs need to be processed by computer programs:
 - * Adjacency matrix
 - * Adjacency list









Adjacency Matrix · (Undirected)

- · If two vertices are connected then a 1 is place in two positions in the matrix:
 - * Find the row for the first vertex, move to the cell in this row which is in the column for the second vertex
 - * Find the row for the second vertex, move to the cell in this row which is in the column for the first vertex



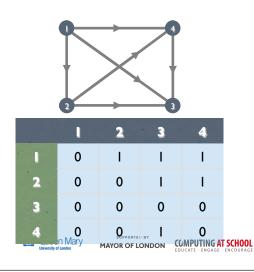
		2	3	4	5
	0	ı	ı	ı	0
2	I	0	0	I	0
3	I	0	0	ı	I
4	I	ı	ı	0	I
5	0	0	ı	ı	0





Adjacency Matrix

- · (Directed)
- Positioning of 1s does not have to be symmetrical





Adjacency List • Undirected Graph:

- · Specifies the vertices that are adjacent to each vertex of the graph

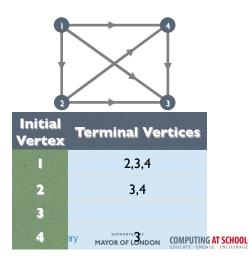


Vertex	Adjacent Vertices	
1	2,3,4	
2	1,4	
3	1,4,5	
4	1,2,3,5	
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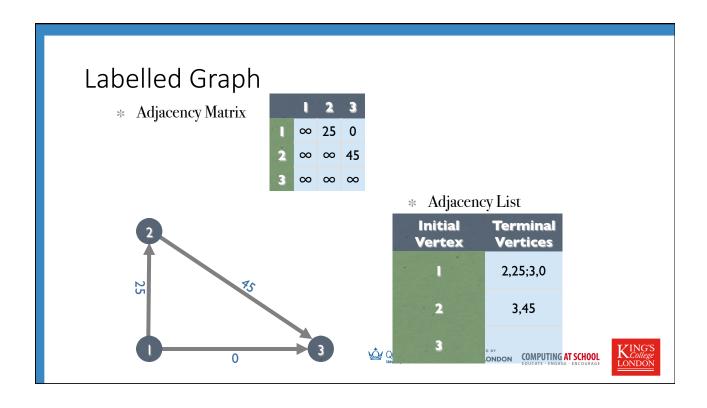


Adjacency List Directed Graph:

- - * Must reflect direction of edges
 - * Adjacent vertices are called terminal vertices
 - * Terminal vertices are adjacent to the initial vertex







When to use adjacency matrices and lists

- Matrix
 - * Use when there are many vertex pairs connected by edges
 - * Indicates edge exists with one access
- List
 - * Use if the graph is sparse (not as many edges)









Activity 1.1 & 1.2

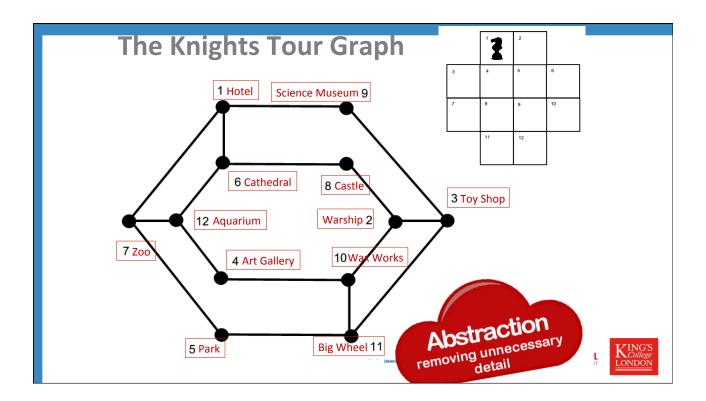
• Which is harder and why?











Exercise 2: A Puzzle

- •
- Boris, Ben, Bob, Bess, Beth and Bill are waiting in a doctor's surgery. Looking around the room, each of them sees that they know some of the other people in the room. Ben knows five of the other people sitting in the room, Bob knows four of the others, Beth and Bill both know three of the others, Bess knows two of the others and Boris only knows one of the other people. Who knows who in the waiting room?
- Solve the puzzle (in pairs) by drawing a graph
- (this is a good starter exercise)



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Step 1

Represent each of the people as a vertex.







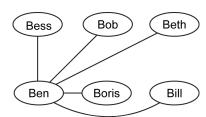






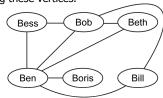
Step 2

Ben knows five of the other people in the room; this means that he knows all the others so draw edges connecting him to the other vertices.



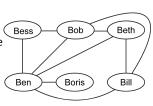
Step 3

Now Boris only knows one other person – we can now tell that this is Ben. Bob knows four other people in the room; we know one of these is Ben and we know that Boris is not one of them so Bob must also know Beth, Bess and Bill. Draw edges representing these vertices.



Step 4

Bess only knows two other people; we can see from our graph that they are Ben and Bob. Bill and Beth both know three other people. From our graph, we can see that they both know Ben and Bob. They do not know Boris or Bess, therefore they must know each other. Draw the edge representing this relationship and the graph has now been completed and shows we will be known who in the waiting room



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Connectivity

- Many applications of graphs involve getting from one vertex to another: e.g.
 - * Finding the shortest route between two places
 - * Finding the route out of a maze
- A graph is connected if there is a path between each pair of vertices
- Otherwise the graph is said to be disconnected





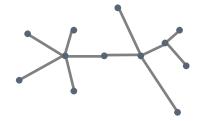


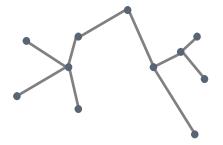


- **All** vertices are connected
- The graph is undirected
- There are no cycles

Rooted Tree

- Has one vertex that has been designated as the root
- Every edge is directed away from the root





Binary Tree

If each node in the tree has a maximum of two children then it is called a binary tree









Binary Search Tree

- ***Sorted Binary Tree:**
 - *left sub-tree contains only nodes with values less than the node's
 - *right sub-tree contains only nodes with values greater than the node's
 - *both left and right sub-trees are binary search trees









Binary Tree Traversal

*Pre order (visit,left, right)

[A, B, C]

★In order (left visit right)

[B,A,C]

*Post order (left, right visit)

*[B,C A]











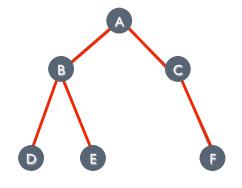
Pre order Binary Tree Traversal

Def pre(tree, start):

Visit node(print?) If node to the left of start: then dft left If node to the right of start:

then dft right

ABDECF









Exercise 3.1

- Complete the Skelton for the pre-order Tree traversal
- 3.2 and 3.3
- Extend with a post and in -order



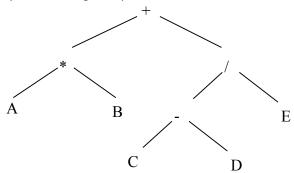






Exercise 4: More traversals

An algebraic expression is represented by the following binary tree.



- Show the output produced if the tree is traversed using:

 +*AB?-CDE
- ❖ pre-order traversal

nost-order traversal

A * B + C - D / E

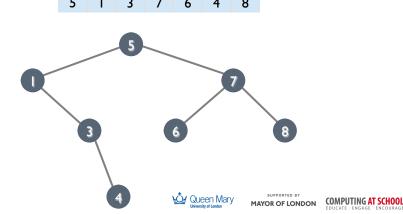
❖ in-order traversal

A B * C D - E A Queen Mary

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Example Binary Search Tresarch algorithms for a BST are very efficient





* stDepoth fFirst traversal

- The Depth First Search (DFS), follows a chain of vertices until it cannot go further, at which point it backs up.
- * This is a pre order traversal

```
def dfspreorder(tree,start):
     if start in tree:
          print(start)
          branches=tree[start]
          #print(branches)
          for i in range(0,len(branches)):
               dfspreorder(tree,branches[i])
This can also been done post order so would output 4,5,3,6,2 in the diagram this will involve a stack!
```

https://commons.wikimedia.org/wiki/File:Depth-first-tree.svg 8 9 12







Breadth First Traversal

- $\label{eq:continuous} \$ \ \ \mbox{Standard Algorithm for searching trees}$
- The Breadth First Search (BFS) visits all neighbours of each vertex before moving on to another vertex.

Breadth-First-Search(Graph, root): create empty set S create empty queue Q root.parent = NIL add root to S Q.enqueue(root) while Q is not empty: current = Q.dequeue() if current is the goal: return current for each node n that is adjacent to current: if n is not in S: add n to S n.parent = current Q.enqueue(n)



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Breadth vs depth

- You met Sam at a friends party and didn't get a number
- You know they must be friends with someone at the party to have been there
- To find Sam Do you depth first or breadth first search your facebook friend?









- DFS
- must see whole tree anyway
- you know d, the level of the answer
- don't care if the answer is closest to root
- BFS
 - answer is close to the root
 - you want the answer that is closest to the root
 - have multiple cores/processors
 - will always find the answer in finite time.....

Will also find you the shortest path to your destination (least number of edges)







Connectivity

- *Many applications of graphs involve getting from one vertex to another: e.g.
 - * Finding the shortest route between two places
 - * Finding the route out of a maze









Connectivity

- *A graph is connected if there is a path between each pair of vertices
- * Else the graph is said to be disconnected









Paths

*Sequence of edge that begins at a vertex of a graph and travels from vertex to vertex along the edges of the graph

* http:// oracleofbacon.org





Dijkstra's (Shortest Path)

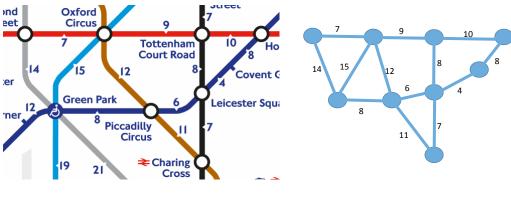








Tueb failure....We need to walk from Bond street to Leicester Square to meet our date....

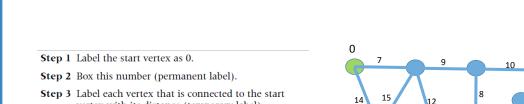




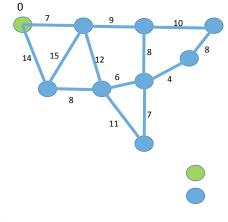
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- vertex with its distance (temporary label).
- Step 4 Box the smallest number.
- Step 5 From this vertex, consider the distance to each connected vertex.
- Step 6 If a distance is less than a distance already at this vertex, cross out this distance and write in the new distance. If there was no distance at the vertex, write down the new distance.
- Step 7 Repeat from step 4 until the destination vertex is boxed.





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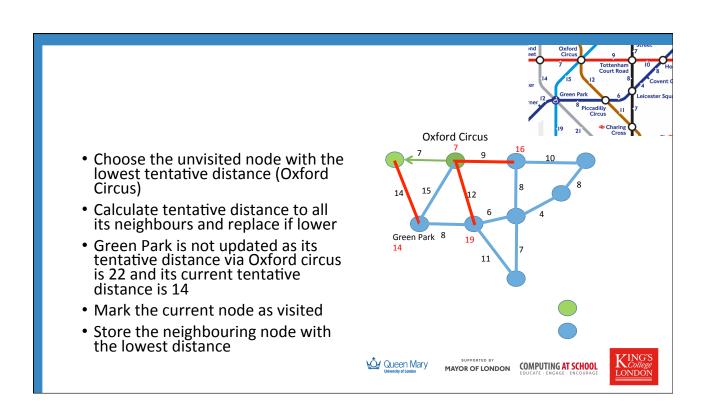
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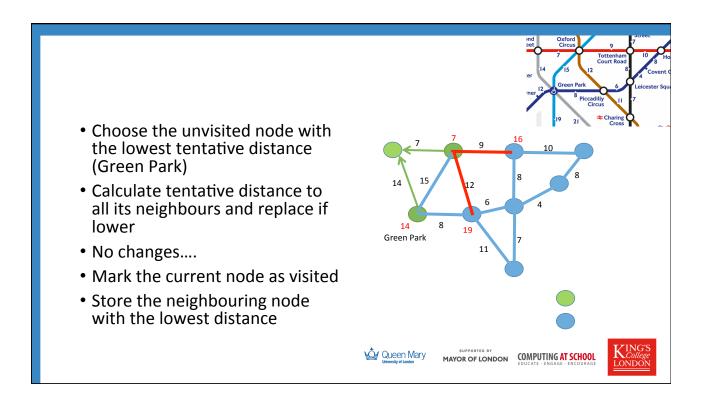


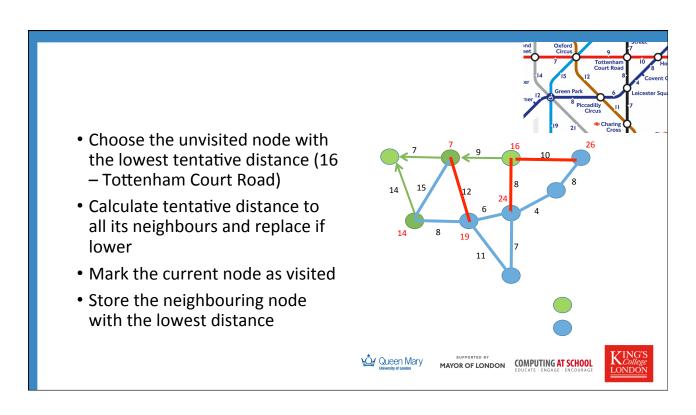
• Look at all unvisited neighbours of the current node and work out the tentative distance from the start

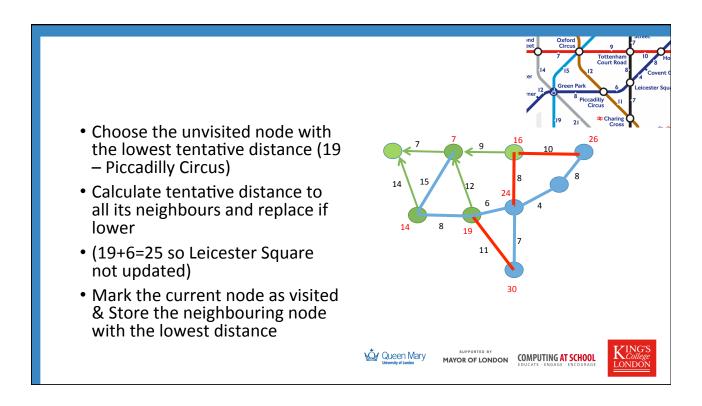
Queen Mary

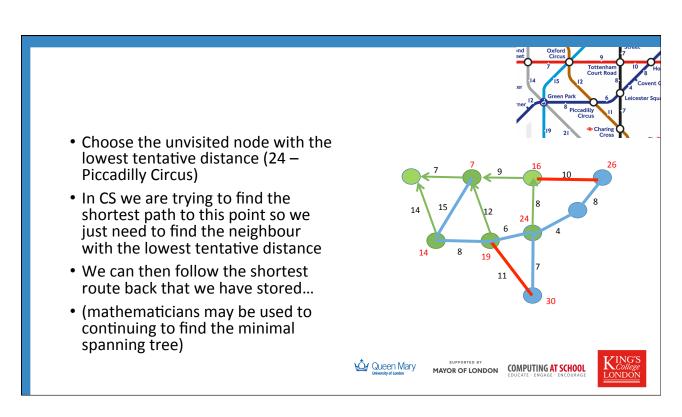
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Exercise 5

- Also
- Interactive example here
- http://optlab-server.sce.carleton.ca/POAnimations2007/ DijkstrasAlgo.html









Comparing Search Algorithms

- Breadth First search Explores equally in all directions
- Dijkstra's Algorithm
 - Favours shorter(cheaper/quicker) paths.
 - calculates the distance from the start point.
- A*- modification of Dijkstra's algorithm
 - prioritises paths in the direction the goal
 - Uses the sum of distance from start and estimated distance from goal..





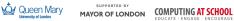


Taking this further....

- http://www.redblobgames.com/pathfinding/a-star/introduction.html
- http://www.redblobgames.com/pathfinding/a-star/ implementation.html
- Computerphile A star Search Algorithm
- https://youtu.be/ySN5Wnu88nE
- Maze Solving
- https://youtu.be/rop0W4QDOUI









Homework & Certificates

- No homework
- No certificates today
- Final homework deadline this time next week
 - (please email me if you are planning on completing the homework)







